FORTE-CM Summer School July 2022

Intro to Smart Contracts, Ethereum and Solidity

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Blockchain Systems

What is a blockchain?

A blockchain is an implementation of a **decentralized ledger**, which is a simple **database of transactions** of *coins* (in some digital currency) between addresses.

- Main characteristics:
 - immutable: cryptographic techniques prevent the ledger from being modified.
 - verifiable: anyone can check that transactions are correct.
 - decentralized: processed by miners (or validators).
- The blockchain technology allows to register information more general than a ledger for payments.

Notion of smart contract

- In particular, blockchain technology can be used to automate some rules usually contained in legal contracts or agreements.
 - ▶ If the blockchain system can guarantee by construction the transactions without any intermediator, then
 - it could also be used for automatically executing the terms of a contract.
- The term smart contract was coined by Nick Szabo, a computer scientist and legal scholar, before blockchain technology was developed:

A **smart contract** is a set of promises, specified in digital form, including protocols within which the parties perform on these promises.¹

¹N. Szabo. Smart Contracts: Building Blocks for Digital Markets, 1996

Ethereum

 A full-fledged computer language would be very appropriate for implementing smart contracts.

Contracts should be executed in a trustworthy environment such as **a blockchain system**. This is the case of **Ethereum**.

- Ethereum is more than just another blockchain system.
- The main goal of Ethereum is to create a protocol for building decentralized applications.
 - ▶ It is able to execute bytecode in a built-in virtual machine.
 - **Ether currency** is used to pay for the execution of contracts and to reward miners for mining new blocks.
- The state in Ethereum is composed of a set of accounts:
 - Externally owned accounts (EOA).
 - ► Contract accounts: Accounts controlled by a smart contract.

Ethereum Contracts

"A contract is a collection of code (its functions) and data (its state) that resides at a specific address on the Ethereum blockchain. Contract accounts are able to pass messages between themselves as well as doing practically Turing complete computation. Contracts live on the blockchain in a Ethereum-specific binary format called Ethereum Virtual Machine (EVM) bytecode."

From https://ethdocs.org/en/latest/contracts-and-transactions/contracts.html

- Code and data reside safe on the Ethereum blockchain.
- Turing complete computation: it allows any arbitrary computation.
- Ethereum Virtual Machine (EVM): Contracts are compiled into a hardware-independent bytecode language.
- Contracts live on the blockchain: executed in a secured environment, in the network nodes.

Ethereum Virtual Machine

- Ethereum includes a virtual machine that executes bytecode (very much like Java VM).
- EVM bytecode is a platform-independent assembly-like language.
- High-level languages compile into EVM bytecode, e.g. Solidity.
- An important problem of a programmable blockchain are infinite computations.
 - ▶ They can be used as a form of DDoS attack.
 - They cannot be checked in advance (unless we manage to solve the halting problem!).
- This problem is overcome in Ethereum with the notion of gas.

The notion of gas

 DoS attacks and infinite computations are prevented by charging the execution of contract bytecode with a fee:

Every EVM instruction consumes some amount of gas.

- Some instructions are more expensive than others (e.g., persistent storage handling).
- Local memory usage also consumes gas.
- When a contract function is invoked, two values are provided:
 - **gasLimit:** the amount of gas available for executing the contract.
 - **gasPrice:** the value of each unit of gas measured in Wei.
- If gasLimit is exceeded, the execution halts with an exception and the entire execution is reverted.

Solidity

- **Solidity** is the most commonly used language for programming contracts in Ethereum.
- The syntax of Solidity is similar to other well-known programming languages (C, Java).
- However, it includes many details imposed by the low-level EVM bytecode language.
- Contracts are similar to classes in object-oriented languages.
- Contracts can contain the following elements (among others):
 - State variables: persistent variables that are stored on Ethereum blockchain storage.
 - **Functions:** define the behaviour of the contract.
 - **Events:** log entries for communicating info to external applications.

Layout of a Solidity source file

```
// SPDX-License-Identifier: GPL-3.0
pragma solidity >=0.7.0 <0.9.0;</pre>
contract Storage {
  uint number; // these are (persistent) state variables
  address owner:
  function store(uint num) public {
    uint double: // this is a local variable
    double = num * 2;
    number = double;
  function retrieve() public view returns (uint) {
    return number;
```

Solidity Data Types

Value data types:

- uint, uint256: 256-bit unsigned integers.
- ▶ int, int256: 256-bit signed integers.
- ▶ uint8, int8, uint16, uint32,...: (un)signed integers of N bits.
- ▶ address: 160-bit Ethereum addresses.

Reference data types:

- ▶ structs
- arrays (fixed- and dynamically-sized)
- mappings (similar to hash tables)

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EVM programs

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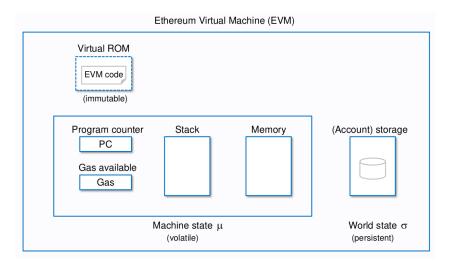


Ethereum Bytecode (EVM)

- Stack based language
- Small set of instructions
 - Arithmetic operations
 - Conditional and unconditional jumps
 - Store and load data
 - Blockchain data
 - Cryptographic hash algorithms for allocating persistent memory
- A specification of the EVM is available:
 - G. Wood, Ethereum: A secure decentralised generalised transaction ledger (EIP-150), 2018.

https://ethereum.github.io/yellowpaper/paper.pdf (latest version)

EVM architecture



 $\textbf{Source:} \ \texttt{https://takenobu-hs.github.io/downloads/ethereum_evm_illustrated.pdf}$

EVM bytecode

- Bytecode language is untyped.
 - ▶ Most instructions operate on 256-bit words as unsigned integers.
 - Specific signed operations (SDIV, SMOD, SIGNEXTEND).
- All invocations start executing the contract with PC = 0.
- Runtime code starts with some memory initializations and the function selector.
 - ▶ A function is identified by a hash of its signature:
 - Example: bytes4 (keccak256 (bytes ("square (uint256)")))
- There is no notion of methods, objects or structs.
- Calls to internal functions are translated to jumps.
- Jump addresses are not constant. They are read from the stack.

EVM calls to internal functions

```
pragma solidity ^0.6.0;

contract mini2 {
  function square(uint n)
  external pure returns(uint) {
    return _square(n);
  }

  function _square(uint n)
  internal pure returns(uint) {
    return n*n;
  }
}
```

```
JUMPDEST
  PUSH 0
  PUSH 8 //tag8
  DUP3
 PUSH 9 //tag9
  TUMP
tag8
  JUMPDEST
  SWAP1
  POP
  SWAP2
  SWAP1
  POP
  JUMP //out
```

```
tag9 //_square
JUMPDEST
PUSH 0
DUP2
DUP3
MUL
SWAP1
POP
SWAP2
SWAP1
POP
JUMP //out
```

EVM bytecode instructions

• Arithmetic:

ADD, MUL, DIV, SDIV, MOD, SMOD, ADDMOD, MULMOD, EXP, SIGNEXTEND

Comparison and bitwise logic:

LT, GT, SLT, SGT, EQ, ISZERO, AND, OR, XOR, NOT, BYTE, SHL, SHR, SAR

- Environmental information: ADDRESS, BALANCE, ORIGIN, CALLER, etc.
- Stack: POP, PUSHi, DUPj, SWAPj (i <= 32, j <= 16)
- Memory: MLOAD, MSTORE
- Storage: SLOAD, SSTORE
- Block information: BLOCKHASH, COINBASE, GASLIMIT, etc.
- Flow: JUMP (unconditional jump), JUMPI (conditional jump), JUMPDEST (jump destination)
- Hash computation: SHA3
- System: CREATE, CALL, DELEGATECALL, RETURN, REVERT, STOP, INVALID, SELFDESTRUCT, etc.

EVM bytecode

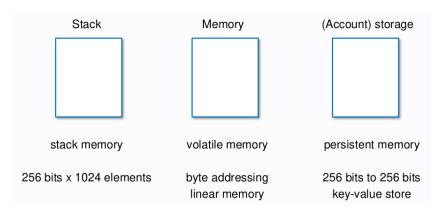
Notion of block

"A maximal sequence of straight-line consecutive code in the program with the properties that the flow of control can only enter the block through the first instruction in the block, and can only leave the block at the last instruction."

 Blocks are the nodes in the control-flow graph (CFG) of the contract.

EVM memory regions

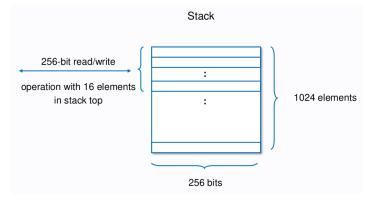
• There are several memory regions:



Source: https://takenobu-hs.github.io/downloads/ethereum_evm_illustrated.pdf

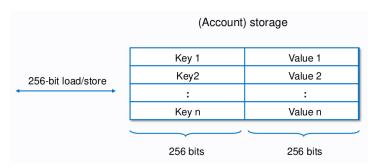
EVM stack

- EVM is a stack-based virtual machine:
 - ▶ There are no registers, just a stack with 1024 256-bit words.
 - ▶ Most instructions operate on the top-most elements in the stack.
 - Contains value-type local variables, intermediate values and jump addresses.
 - ► **Gas consumption:** Operations on stack are **very cheap.**



EVM storage

- Persistent memory region.
- Each contract can only access its own storage.
- Implemented as a collection of (key,value) pairs.
- Stores any data type: value types, structs, arrays, mappings.
- Gas consumption: Expensive to use (the price of persistence).

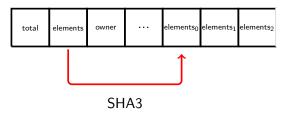


 ${\bf Source: https://takenobu-hs.github.io/downloads/ethereum_evm_illustrated.pdf}$

Storage layout

- State variables are stored in consecutive positions starting at 0.
- Value types are stored directly, packing them tightly if possible.
- Arrays are stored differently:
 - Array length is stored in its corresponding slot.
 - Array contents are stored at location SHA3(slot).

Storage:



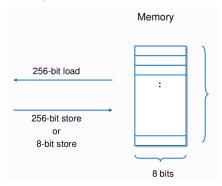
Storage operations

```
contract StAccesses {
  uint total;
  uint[] elems;
  address owner:
  function fn(uint n) external {
    for (uint i=0; i<n; i++) {</pre>
      elems.push(0x97);
    total = 13;
    owner = msg.sender;
```

```
SLOAD
          //elems.length
ADD
          //length+1
DUP1
DUP3
SSTORE
          //elems.length
KECCAK256 //addr(elems[0])
ADD //addr(elems[length-1])
. . .
SSTORE
         //elems[length-1]
. . .
PUSH D
PUSH 0
DUP 2
SWAP1
SSTORE //store total
. . .
```

EVM memory

- Volatile memory region for local computations:
 - Fresh memory for each external function call.
 - Stores reference-type local variables (structs, arrays).
 - ▶ Required by some instructions (SHA3, arguments of external calls).
 - ► **Gas consumption:** Cheaper than storage, but gas increases with the amount of memory used.



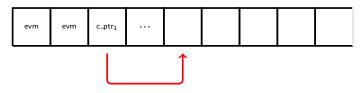
- Memory address 0x40 contains a pointer to the first free memory location.
 - It is increased for each variable.
 - ► Each basic value is stored in a 256-bit word (regardless of its size).
- It is **never freed**. Cleared for each external call.
- Arrays are stored next to their length.
- Pointers are used for nested data structures.

```
contract Accesses {
   struct StrType { uint str1; uint str2; }

   function fnMemory() external pure {
     StrType memory st=StrType(15,11);
     uint[] memory arr1=new uint[](7);
     //...
}
```

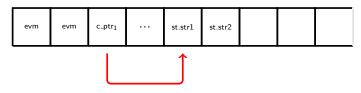
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   struct StrType { uint str1; uint str2; }

  function fnMemory() external pure {
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    uint[] memory arr1=new uint8[](7);
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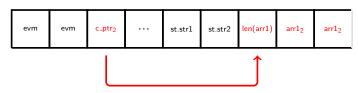
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Memory operations

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    //...
```

```
PUSH 40
DUP1
MLOAD // ptr=mem[0x40]
SWAP1
DUP2
ADD
PUSH 40
MSTORE //mem[0x40] = ptr + 0x40
DUP 1
PUSH F
DUP 2
MSTORE //mem[ptr] = 15
PUSH 20 // (st.str1)
ADD
PUSH B
DUP 2
MSTORE //mem[ptr+0x20]=11
... // (st.str2)
```

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Analysis of Smart Contracts Gas Analysis of Ethereum Smart Contracts

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+Efficient Smart Contracts

Efficiency-related properties:

- 1. Estimate the gas consumption (static analysis)
 - ► Goal: avoid gas-related vulnerabilities (GASTAP)
- 2. Optimize the gas consumption (synthesis)
 - ► Goal: reduce transaction costs (GASOL)

GAS-METERED EXECUTION

• Gas-limit: amount of gas allowed to carry out transaction.

Gas-Metered Execution

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300.000

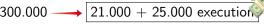
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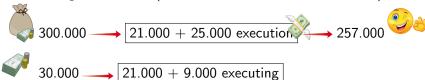
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30.000

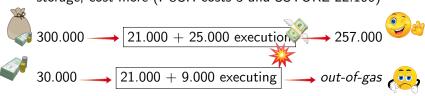
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- Rationale of gas metering :
 - prevents attacks based on non-terminating executions;
 - avoids wasting miners computational resources;
 - discourages users to overuse replicated storage

WHAT IS GASTAP?

Gastap

GASTAP is a framework that given a smart contract infers gas upper bounds for all its public functions

```
contract EthereumPot {
   address public owner;
   address[] public addresses;
   address public winnerAddress;
   uint[] public slots;
   ...
   function findWinner(uint random) constant returns(address winner){
     for(uint i = 0; i < slots.length; i++) {
        if (random <= slots[i]) {
            return addresses[i];
        }}
   ...
}</pre>
```

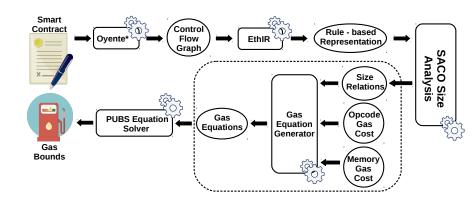
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        }}
   ...
}</pre>
```

ARQUITECTURE OF GASTAP



WHAT IS ETHIR?

ETHIR

EthIR is a framework that translates Ethereum bytecode into an intermediate representation.

Ethereum Bytecode

- Stack based language.
- Small set of instructions.

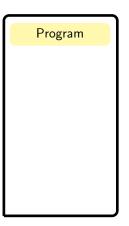
PUSH 0X01 PUSH 0X04 ADD PUSH 0X000F JUMP

• Why do we work at bytecode level?

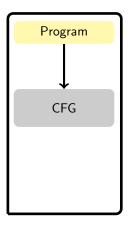
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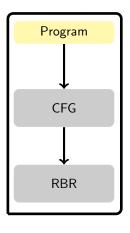
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 - ▶ The source code of the smart contracts is not available
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 - Information only available at bytecode level
 - ★ Gas consumption
 - Analyses may be affected by compiler optimizations
 - Binary arithmetic, unfolding, etc.



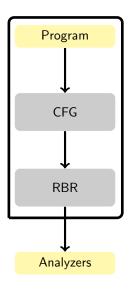
 Program: Solidity, EVM Bytecode or Disassembly code.



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 Make explicit the stack, memory, fields variables.



- Program: Solidity, EVM Bytecode or Disassembly code.
- CFG: Detect jump addresses
- RBR: Rule based Representation.
 Make explicit the stack, memory, fields variables.
- Analyzers: The RBR can be injected straightforward to existing analyzers with minor changes.

```
start address: 187
contract Loop{
                                                   end address: 210
                                                   type: uncond
                                                   jump target: 179
 uint sum = 0;
                                                   PUSH1 0x01
                                                   SLOAD 1
  uint number = 5;
                                                   PUSH1 0x00
                                                   SLOAD 0
                                                   ADD
  function multiply(uint a){
                                                   PUSH1 0x00
    for(uint i = 0; i < a; i++){
                                                   DUP2
                                                   SWAP1
      sum = sum+number;
                                                   SSTORE 0
                                                   PUSH1 0xb3
                                                   IUMP
```

- We generate the CFG of the smart contract including annotations
 - SSTORE, SSLOAD, MSTORE, MLOAD, CALLDATALOAD...

How does EthIR work?

start address: 187
end address: 210
type: uncond
jump target: 179
PUSH1 0x01
SLOAD 1
PUSH1 0x00
SLOAD 0
ADD
PUSH1 0x00
DUP2
SWAP1
SSTORE 0
...

JUMP

```
block187(s(3), s(2), s(1), s(0), g(1), g(0)) \Rightarrow
s(4) = 1
s(4) = g(1)
s(5) = 0
s(5) = g(0)
s(4) = s(5)+s(4)
s(5) = 0
s(6) = s(4)
s(7) = s(5)
s(5) = s(6)
s(6) = s(7)
g(0) = s(5)
...
s(4) = 179
call(block179(s(3),s(2),s(1),s(0),g(1), g(0)))
```

How does EthIR work?

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start address: 187
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SLOAD 1
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ADD
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SWAP1
SSTORE 0
...
PUSH1 0xb3
JUMP
```

```
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```

Each block corresponds to one rule.

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start address: 187
end address: 210
type: uncond
jump target: 179
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SLOAD 1
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SLOAD 0
ADD
PUSH1 0x00
DUP2
SWAP1
SSTORE 0
...
PUSH1 0xb3
JUMP
```

```
block187(s(3), s(2), s(1), s(0) g(1), g(0)) \Rightarrow s(4) = 1 s(4) = g(1) s(5) = 0 s(5) = g(0) s(4) = s(5)+s(4) s(5) = 0 s(6) = s(4) s(7) = s(5) s(5) = s(6) s(6) = s(7) g(0) = s(5) ... s(4) = 179 call(block179(s(3),s(2),s(1),s(0),g(1), g(0)))
```

- Each block corresponds to one rule.
- The fields and data are passed to the rules as parameters.

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start address: 187
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SLOAD 1
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SLOAD 0
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```

```
block187(3), s(2), s(1), s(0) g(1), g(0)) \Rightarrow
s(4) = 1
s(4) = g(1)
s(5) = 0
s(5) = g(0)
s(4) = s(5) + s(4)
s(5) = 0
s(6) = s(4)
s(7) = s(5)
s(5) = s(6)
s(6) = s(7)
g(0) = s(5)
...
s(4) = 179
call(block179(s(3), s(2), s(1), s(0), g(1), g(0)))
```

- Each block corresponds to one rule.
- The fields and data are passed to the rules as parameters.
- Stack variables are explicit in the code.

```
start address: 187
end address: 210
type: uncond
jump target: 179
PUSH1 0x01
SLOAD 1
PUSH1 0x00
SLOAD 0
ADD
PUSH1 0x00
DUP2
SWAP1
SSTORE 0
...
PUSH1 0xb3
JUMP
```

```
\begin{array}{l} \mathsf{block187}(\mathsf{s}(3),\,\mathsf{s}(2),\,\mathsf{s}(1),\,\mathsf{s}(0),\,\mathsf{g}(1),\,\mathsf{g}(0)) \ \Rightarrow \\ \mathsf{s}(4) = 1 \\ \mathsf{s}(4) = \mathsf{g}(1) \\ \mathsf{s}(5) = 0 \\ \mathsf{s}(5) = \mathsf{g}(0) \\ \mathsf{s}(4) = \mathsf{s}(5) + \mathsf{s}(4) \\ \mathsf{s}(5) = 0 \\ \mathsf{s}(6) = \mathsf{s}(4) \\ \mathsf{s}(7) = \mathsf{s}(5) \\ \mathsf{s}(5) = \mathsf{s}(6) \\ \mathsf{s}(6) = \mathsf{s}(7) \\ \mathsf{g}(0) = \mathsf{s}(5) \\ \dots \\ \mathsf{s}(4) = 179 \\ \mathsf{call}(\mathsf{block179}(\mathsf{s}(3),\!\mathsf{s}(2),\!\mathsf{s}(1),\!\mathsf{s}(0),\!\mathsf{g}(1),\,\mathsf{g}(0))) \end{array}
```

- Each block corresponds to one rule.
- The fields and data are passed to the rules as parameters.
- Stack variables are explicit in the code.
- Jump instructions are converted to calls to new blocks.

start address: 175
end address: 170
type: cond
jump target: 189
falls to: 171
JUMPDEST
PUSH1 0x05
PUSH1 0x01
DUP2
SWAP1
SSTORE 1
PUSH1 0xab
LT
PUSH1 0xbd
JUMP1

```
block175(s(3), s(2), s(1), s(0), g(1), g(0)) \Rightarrow
    s(4) = 5
    s(5) = 1
    s(6) = s(4)
    s(7) = s(6)
    s(6) = s(5)
    s(5) = s(7)
    g(1) = s(5)
    s(4) = 171
    call(jump175(s(4),s(3),s(2),s(1),s(0),g(1),g(0)))
jump175(s(4),s(3),s(2),s(1),s(0),g(1),g(0)) \Rightarrow
    lt(s(4),s(3))
    call(block189(s(2),s(1),s(0),g(1)))
[jump179(s(4),s(3),s(2),s(1),s(0),g(1),g(0))] \Rightarrow
    geq(s(4),s(3))
    call(block171(s(2),s(1),s(0),g(1),g(0)))
```

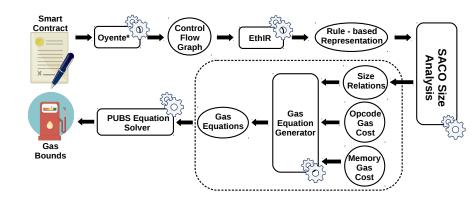
- Each block corresponds to one rule.
- The fields and data are passed to the rules as parameters.
- Stack variables are explicit in the code.
- Jump instructions are converted to calls to new blocks.

```
start address: 187
end address: 210
type: uncond
jump target: 179
PUSH1 0x01
PUSH1 0x00
SLOAD 1
PUSH1 0x00
SLOAD 0
ADD
PUSH1 0x00
DUP2
SWAP1
SSTORE 0
...
PUSH1 0xb3
JUMP
```

```
block187(s(3), s(2), s(1), s(0), g(1), g(0)) \Rightarrow
   s(4) = 1 nop(PUSH1)
   s(4) = g(1)
                nop(SLOAD)
   s(5) = 0 nop(PUSH1)
   s(5) = g(0) \quad nop(SLOAD)
   s(4) = s(5) + s(4) nop(ADD)
   s(5) = 0 nop(PUSH1)
   s(6) = s(4)
                nop(DUP2)
   s(7) = s(5)
   s(5) = s(6)
   s(6) = s(7)
                nop(SWAP1)
   g(0) = s(5) nop(SSTORE)
   s(4) = 179 \quad nop(PUSH1)
   call(block179(s(3),s(2),s(1),s(0),g(1), g(0)))
   nop(JUMP)
```

- Each block corresponds to one rule.
- The fields and data are passed to the rules as parameters.
- Stack variables are explicit in the code.
- Jump instructions are converted to calls to new blocks.
- nop instructions for the cost model.

ARQUITECTURE OF GASTAP



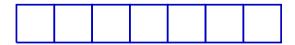
- Generated using the RBR and SR
- It depends on the opcodes executed and the memory used during the transaction
 - Memory Gas.
 - Opcode Gas.

$$Gas(i) = C_{mem}(\mu'_i) - C_{mem}(\mu_i) + C_{opcode}(i)$$

- Gas consumed by EVM instruction i.
- μ'_i and μ_i are the highest memory slot accessed after and before the execution of the opcode at program point i, resp.

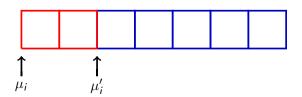
$$Gas(i) = C_{mem}(\mu'_i) - C_{mem}(\mu_i) + C_{opcode}(i)$$

$$C_{mem}(a) = 3 \cdot a + \left\lfloor \frac{a^2}{512} \right\rfloor$$



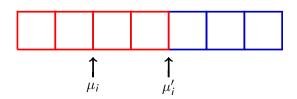
$$\mathsf{Gas}(\mathsf{i}) = C_{mem}(\mu_i) - C_{mem}(\mu_i) + C_{opcode}(i)$$

$$C_{mem}(a) = 3 \cdot a + \left\lfloor \frac{a^2}{512} \right\rfloor$$



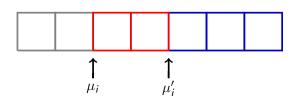
$$\mathsf{Gas}(\mathsf{i}) = \mathit{C}_{mem}(\mu_i') \text{-} \mathit{C}_{mem}(\mu_i) + \mathit{C}_{opcode}(\mathit{i})$$

$$C_{mem}(a) = 3 \cdot a + \left\lfloor \frac{a^2}{512} \right\rfloor$$



$$\mathsf{Gas}(\mathsf{i}) = \mathit{C}_{mem}(\mu_i') \text{-} \mathit{C}_{mem}(\mu_i) + \mathit{C}_{opcode}(\mathit{i})$$

$$C_{mem}(a) = 3 \cdot a + \left\lfloor \frac{a^2}{512} \right\rfloor$$



Memory Gas

$$Gas(i) = C_{mem}(\mu_i) - C_{mem}(\mu_i) + C_{opcode}(i)$$

$$C_{mem}(a) = 3 \cdot a + \left\lfloor \frac{a^2}{512} \right\rfloor$$

The sum of all memory gas cost \equiv the memory cost function for the highest slot accessed

Opcode Gas

$$Gas(i) = C_{mem}(\mu'_i) - C_{mem}(\mu_i) + C_{opcode}(i)$$

- Each opcode has a fee associated:
 - Most of them are constant: JUMP(8)*, ADD(3), MLOAD(3), etc.
 - ▶ Different constant gas depending on some condition: SLOAD(100 / 2100)*, SSTORE (100 to 22100)*, etc.
 - ▶ Non-constant gas consumption: EXP, SHA3, etc.
 - * These fees changed after Berlin hard fork.

Opcode Gas

Constant gas

$$Gas(i) = C_{mem}(\mu'_i) - C_{mem}(\mu_i) + C_{opcode}(i)$$

They can be classified in 8 groups:

- Zero (0): STOP, RETURN, REVERT
- Base (2): POP, GAS, CALLER, ADDRESS,...
- VeryLow (3): ADD, SUB, LT, EQ, PUSH, MLOAD, MSTORE,...
- Low (5): MUL, DIV, MOD, SMOD,...
- Mid (8): ADDMOD, MULMOD, JUMP
- High (10): JUMPI
- Extcode (700): EXTCODESIZE
- Others: JUMPDEST(1), CREATE(32000),...

Opcode Gas

Constant gas depending on some condition

$$Gas(i) = C_{mem}(\mu'_i) - C_{mem}(\mu_i) + C_{opcode}(i)$$

When loading some value form address pos:

$$SLOAD = \begin{cases} 100 & \text{if storage(pos) previously accessed (in the current or a 2100 otherwise} \end{cases}$$

SSTORE has a more complex constant gas expression that depends on several conditions (see Yellow Paper):

- The location has been accessed in a previous transaction,
- it has been already modified in this transaction,
- and the value being assigned to that storage location.

GAS EQUATIONS

Opcode Gas

Non-constant gas

$$\mathsf{Gas}(\mathsf{i}) = C_{mem}(\mu_i') - C_{mem}(\mu_i) + C_{opcode}(i)$$

• EXP =
$$10 + 50 \cdot (1 + \lfloor log_{256}(stack[top - 1]) \rfloor)$$

- SHA3 = $30 + 6 \cdot \lceil stack[top 1] \div 32 \rceil$
- LOG3 = $375 + 8 \cdot stack[top 1] + 3 \cdot 375$
- . .

GAS EQUATIONS

$$Gas(i) = C_{mem}(\mu_i) - C_{mem}(\mu_i) + C_{opcode}(i)$$

- Each rule is transformed into a cost equation
- Nop instructions determine the gas consumed
- Calls to other rules replaced to cost equations
- Size relations attached
- PUBS Solver: Generation of a closed-form gas upper bound

```
\begin{array}{l} \mathsf{block1619}(\mathsf{s}(4),\cdots,\mathsf{s}(0),\mathsf{g}(3),\mathsf{g}(1),\mathsf{I}(|2),\mathsf{I}(|1),\mathsf{I}(|0)) \Rightarrow \\ \mathsf{s}(5) = 3 \quad \mathsf{nop}(\mathsf{PUSH1}) \\ \mathsf{s}(6) = \mathsf{s}(5) \quad \mathsf{nop}(\mathsf{DUP1}) \\ \mathsf{s}(6) = \mathsf{g}(3) \quad \mathsf{nop}(\mathsf{SLOAD}) \\ \cdots \\ \mathsf{s}(6) = \mathsf{s}(4) \quad \mathsf{nop}(\mathsf{DUP2}) \\ \mathsf{call}(\mathsf{jump1619}(\mathsf{s}(6),\cdots,\mathsf{s}(0),\mathsf{g}(3),\;\;\mathsf{g}(1),\mathsf{I}(|2),\;\;\mathsf{I}(|1),\;\;\mathsf{I}(|0))) \\ \mathsf{nop}(\mathsf{LT}) \quad \mathsf{nop}(\mathsf{ISZERO}) \quad \mathsf{nop}(\mathsf{PUSH2}) \quad \mathsf{nop}(\mathsf{JUMPI}) \end{array}
```

```
block1619(s(4),..., s(0), g(3), g(1), I(12),...) \Rightarrow 234+jump1619(s(6),...,s(0),g(3), g(1),...) {s(6) = s(4), s(5) = g(3)}
```

GAS EQUATIONS

- We compute the memory gas cost and opcode gas cost separately
 - Memory gas cost: Infer the highest slot of memory accesed by the opcodes executed in the function
 - ▶ Opcode gas: Compute gas equations

Total gas consumption = Memory gas + Opcode gas

PRACTICE WITH GASTAP

GASTAP can be found at https://costa.fdi.ucm.es/gastap/

- 1. Load into GASTAP the following contract and analyze it.
 - ► Copy the code on Gastap central panel and press Refresh Outline.
 - ► Then Select one function on the right and press **Apply**. Analyze the contract functions one by one.
- 2. Explain the results obtained for these functions.

```
pragma solidity ^0.4.0;
contract exercise3 {
    uint [] arr = new uint[](5);
    function p1() external view returns (uint) {
        uint sumEven = 0;
        for (uint i = 0; i < arr.length; i+=2) {
            sumEven += arr[i];
        }
        return sumEven;
    }
    function p2() external view { uint [] memory local = arr; }
    function p3() external view { uint [] storage local = arr; }
}</pre>
```

GASOL: GAS ANALYSIS TOOLKIT

Goal: Optimization of gas consumption. It works at two levels:

- 1. Solidity level: It uses resource analysis to reduce the accesses to storage.
- 2. EVM bytecode level: It uses superoptimization to find equivalent bytecode that produces the same state but consuming less gas.

Original program:

```
for (uint i=0; i<data.length; i++) {
   address a = address( data[i] & (D160-1) );
   uint amount = data[i] / D160;
   if (balanceOf[a] == 0) {
     balanceOf[a] = amount;
     totalSupply = totalSupply + amount;
   }
}</pre>
```

Original program:

```
for (uint i=0; i<data.length; i++) {
   address a = address( data[i] & (D160-1) );
   uint amount = data[i] / D160;
   if (balanceOf[a] == 0) {
     balanceOf[a] = amount;
     totalSupply = totalSupply + amount;
   }
}</pre>
```

Original program:

Accesses to totalSupply

```
for (uint i=0; i<data.length; i++) {
   address a = address( data[i] & (D160-1) );
   uint amount = data[i] / D160;
   if (balanceOf[a] == 0) {
     balanceOf[a] = amount;
     totalSupply = totalSupply + amount;
   }
}</pre>
```

2*data

Original program:

```
for (uint i=0; i<data.length; i++) {
   address a = address( data[i] & (D160-1) );
   uint amount = data[i] / D160;
   if (balanceOf[a] == 0) {
     balanceOf[a] = amount;
     totalSupply = totalSupply + amount;
   }
}</pre>
```

Accesses to totalSupply

2*data

Sound transformation?

Original program:

```
for (uint i=0; i<data.length; i++) {
   address a = address( data[i] & (D160-1) );
   uint amount = data[i] / D160;
   if (balanceOf[a] == 0) {
     balanceOf[a] = amount;
     totalSupply = totalSupply + amount;
   }
}</pre>
```

Accesses to totalSupply

2*data

Optimized program:

```
uint totalSupply_mem = totalSupply;
for (uint i=0; idata.length; i++) {
   address a = address( data[i] & (D160-1) );
   uint amount = data[i] / D160;
   if (balanceOf[a] == 0) {
     balanceOf[a] = amount;
     totalSupply_mem = totalSupply_mem + amount;
   }
}
totalSupply = totalSupply_mem;
```

Sound transformation? Yes

What are the difficulties?

- Detect the pattern
 - ensure effectiveness
- Guarantee soundness
 - global data not reachable by transitive calls
 - analysis that can be done with different precision levels
- Implementation
 - analysis performed on the EVM
 - changes made in the Solidity

GASOL: EVM LEVEL (SUPEROPTIMIZATION)

Superoptimization

Superoptimization is a transformation technique that aims to find the (cost-optimal) translation of a code by trying all posible sequences of instructions that produce the same result.

GASOL: EVM LEVEL (SUPEROPTIMIZATION)

Superoptimization

Superoptimization is a transformation technique that aims to find the (cost-optimal) translation of a code by trying all posible sequences of instructions that produce the same result.

- given: source program s and a cost function C
- find: target program t that
 - has minimal cost C(t)
 - correctly implements s
- using: constraint solver



Gas and bytes-size superoptimization tool that uses symbolic execution, dependency analysis and a Max-SMT solver for stack/memory/storage optimization



Gas and bytes-size superoptimization tool that uses symbolic execution, dependency analysis and a Max-SMT solver for stack/memory/storage optimization

SWAP1 PUSH1 0 MSTORE PUSH1 32 MSTORE ISZERO



Gas and bytes-size superoptimization tool that uses symbolic execution, dependency analysis and a Max-SMT solver for stack/memory/storage optimization

SWAP1 PUSH1 0 MSTORE PUSH1 32 MSTORE ISZERO 18 gas 8 bytes



Gas and bytes-size superoptimization tool that uses symbolic execution, dependency analysis and a Max-SMT solver for stack/memory/storage optimization

SWAP1
PUSH1 0
MSTORE
PUSH1 32
MSTORE
ISZERO

N

18 gas 8 bytes

Stack

ISZERO(s2)

Memory

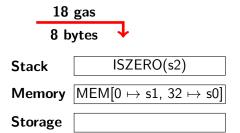
 $\mathsf{MEM}[0 \mapsto \mathsf{s1}, 32 \mapsto \mathsf{s0}]$

Storage



Gas and bytes-size superoptimization tool that uses symbolic execution, dependency analysis and a Max-SMT solver for stack/memory/storage optimization

SWAP1 PUSH1 0 MSTORE PUSH1 32 MSTORE ISZERO

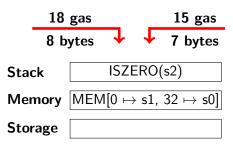


PUSH1 32 MSTORE PUSH1 0 MSTORE ISZERO



Gas and bytes-size superoptimization tool that uses symbolic execution, dependency analysis and a Max-SMT solver for stack/memory/storage optimization

SWAP1 PUSH1 0 MSTORE PUSH1 32 MSTORE ISZERO



PUSH1 32 MSTORE PUSH1 0 MSTORE ISZERO

 Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG

- Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG
- Obtained by symbolic execution from the initial stack

		Stack
PUSH1 96 SWAP2 SWAP1 SWAP2 SHL PUSH1 1 PUSH1 1 PUSH1 96	SHL SUB NOT AND PUSH1 128 MSTORE PUSH1 160 MSTORE	s0 s1 Memory

 Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG

Stack

		Stack
→ PUSH1 96 SWAP2 SWAP1 SWAP2 SHL PUSH1 1 PUSH1 1 PUSH1 96	SHL SUB NOT AND PUSH1 128 MSTORE PUSH1 160 MSTORE	96 s0 s1 Memory

 Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG

Ctack

PUSH1 96 SHL → SWAP2 SUB SWAP1 NOT	
SWAP1 NOT s0 SWAP2 AND 96 SHL PUSH1 128 Memory PUSH1 1 MSTORE Memory PUSH1 96 MSTORE MSTORE MSTORE MSTORE MSTORE PUSH1 96 MSTORE MSTORE PUSH1 96 MSTORE MSTORE PUSH1 96 MSTORE MSTORE PUSH2 MSTORE MSTORE MSTORE PUSH3 MSTORE MSTORE MSTORE	,

 Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG

Stack

		Stack
PUSH1 96 SWAP2 → SWAP1 SWAP2 SHL PUSH1 1 PUSH1 1 PUSH1 96	SHL SUB NOT AND PUSH1 128 MSTORE PUSH1 160 MSTORE	s0 s1 96 Memory

- Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG
- Obtained by symbolic execution from the initial stack

		Stack
PUSH1 96 SWAP2 SWAP1 → SWAP2 SHL PUSH1 1 PUSH1 1 PUSH1 96	SHL SUB NOT AND PUSH1 128 MSTORE PUSH1 160 MSTORE	96 s1 s0 Memory

- Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG
- Obtained by symbolic execution from the initial stack

		Stack
PUSH1 96 SWAP2 SWAP1 SWAP2 → SHL PUSH1 1 PUSH1 1 PUSH1 96	SHL SUB NOT AND PUSH1 128 MSTORE PUSH1 160 MSTORE	SHL(96, s1) s0 Memory

 Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG

Ctack

		Stack
PUSH1 96 SWAP2 SWAP1 SWAP2 SHL	SHL SUB NOT AND PUSH1 128 MSTORE	SHL(96, s1) s0
PUSH1 1		Memory
PUSH1 1 PUSH1 96	PUSH1 160 MSTORE	

 Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG

Stack

		Stack
PUSH1 96 SWAP2 SWAP1 SWAP2 SHL PUSH1 1	SHL SUB NOT AND PUSH1 128 MSTORE	1 1 SHL(96, s1) s0 Memory
PUSH1 1 PUSH1 96	PUSH1 160 MSTORE	

 Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG

Stack

		5 0 0 0 0 0 0
		96
PUSH1 96	SHL	1
SWAP2	SUB	1
SWAP1 SWAP2	NOT AND	SHL(96, s1)
SHL	PUSH1 128	s0
PUSH1 1	MSTORE	Memory
PUSH1 1	PUSH1 160	
PUSH1 96	MSTORE	

- Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG
- Obtained by symbolic execution from the initial stack

Stack SHL(96, 1) 1 SHL(96, s1) s0 Memory

 \rightarrow SHI

SUB

NOT

AND

PUSH1 128

PUSH1 160

MSTORE

MSTORE

PUSH1 96

SWAP2

SWAP1

SWAP2

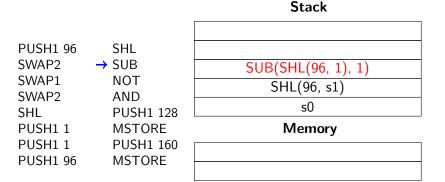
PUSH1 1

PUSH1 1

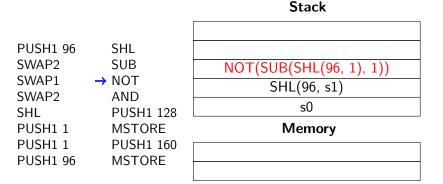
PUSH1 96

SHI

- Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG
- Obtained by symbolic execution from the initial stack



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- Obtained by symbolic execution from the initial stack



 Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG

Stack

		Stack
PUSH1 96 SWAP2 SWAP1 SWAP2 SHL PUSH1 1 PUSH1 1 PUSH1 96	SHL SUB NOT → AND PUSH1 128 MSTORE PUSH1 160 MSTORE	AND(NOT(SUB(SHL(96, 1), 1)),) s0 Memory

 Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG

Stack

	Stack
SHL SUB NOT AND → PUSH1 128 MSTORE PUSH1 160 MSTORE	128 AND(NOT(SUB(SHL(96, 1), 1)),) s0
	Memory
	SUB NOT AND → PUSH1 128 MSTORE PUSH1 160

 Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG

Ctack

		Stack
PUSH1 96 SWAP2 SWAP1 SWAP2 SHL PUSH1 1	SHL SUB NOT AND PUSH1 128 → MSTORE PUSH1 160	s0 Memory
PUSH1 96	MSTORE	MSt(128, AND(NOT(SUB(SHL(96,1),1)),))
. 00.11 30	s r one	

 Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG

Stack

		Stack
PUSH1 96 SWAP2 SWAP1 SWAP2 SHL PUSH1 1 PUSH1 1 PUSH1 96	SHL SUB NOT AND PUSH1 128 MSTORE → PUSH1 160 MSTORE	160 s0 Memory MSt(128, AND(NOT(SUB(SHL(96,1),1)),))
		1

 Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG

Ctack

• Obtained by symbolic execution from the initial stack

		Stack
PUSH1 96 SWAP2 SWAP1 SWAP2 SHL	SHL SUB NOT AND PUSH1 128	
PUSH1 1	MSTORE	Memory
PUSH1 1 PUSH1 96	PUSH1 160 → MSTORE	MSt(128, AND(NOT(SUB(SHL(96,1),1)),))
FU3HI 90	- IVISTORE	MSt(160, s0)

- Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG
- Obtained by symbolic execution from the initial stack
- Simplification rules based on semantics of bytecodes: integers, units, idempotence...

 Stack

PUSH1 96	SHL	
SWAP2	SUB	
SWAP1	NOT	
SWAP2	AND	
SHL	PUSH1 128	
PUSH1 1	MSTORE	Memory
PUSH1 1	PUSH1 160	MSt(128, AND(NOT(SUB(SHL(96,1),1)),))
PUSH1 96	MSTORE	, , , , , , , , , , , , , , , , , , , ,
		MSt(160, s0)

- Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG
- Obtained by symbolic execution from the initial stack
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 Stack

PUSH1 96	SHL	
SWAP2	SUB	
SWAP1	NOT	
SWAP2	AND	
SHL	PUSH1 128	
PUSH1 1	MSTORE	Memory
PUSH1 1	PUSH1 160	MSt(128, AND(NOT(SUB(SHL(96,1),1)),))
PUSH1 96	MSTORE	
		MSt(160, s0)

- Functional description of the final Stack and Memory and Storage (SMS) in terms of the initial stack after executing the instructions in each block of the CFG
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 Stack

PUSH1 96	SHL	
SWAP2	SUB	
SWAP1	NOT	
SWAP2	AND	
SHL	PUSH1 128	
PUSH1 1	MSTORE	Memory
PUSH1 1	PUSH1 160	MSt(128, AND(1.158 × 10 ²⁹ ,))
PUSH1 96	MSTORE	1013t(120, A10D(1.130 × 10 ,))
1 00111 00		MSt(160, s0)

• Static analysis applied to memory for more optimization

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	Stack	tack
 SLOA		
SSTO CALL\	Memor	mory
DUP1		
ISZER	Storage	rage

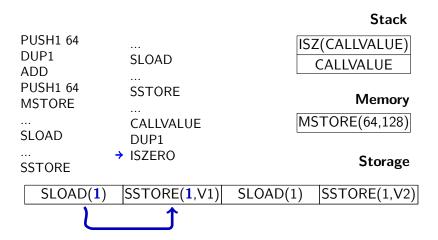
• Static analysis applied to memory for more optimization

			Stack
PUSH1 64 DUP1	 SLOAD	_	Z(CALLVALUE)
ADD PUSH1 64			CALLVALUE
MSTORE	SSTORE 	D. 4.6	Memory
SLOAD	CALLVALUE DUP1	IVIS	STORE(64,128)
 SSTORE	→ ISZERO		Storage
SLOAD(1)	SSTORE(1,V1)	SLOAD(1)	SSTORE(1,V2)

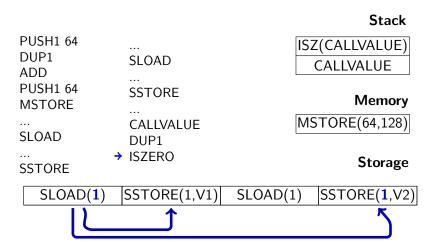
- Static analysis applied to memory for more optimization
- Compute dependencies

				Stack
Е	PUSH1 64 DUP1 ADD	 SLOAD		(CALLVALUE) CALLVALUE
	PUSH1 64 MSTORE	SSTORE 		Memory
S	LOAD	CALLVALUE DUP1	MS	STORE(64,128)
S	STORE	→ ISZERO		Storage
	SLOAD(1)	SSTORE(1,V1)	SLOAD(1)	SSTORE(1,V2)

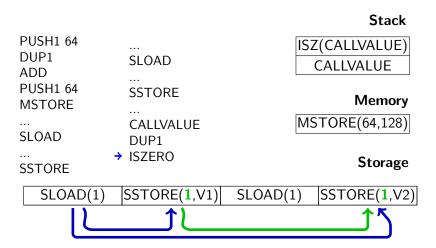
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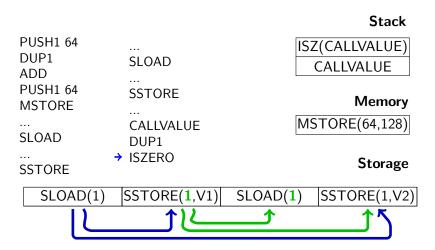
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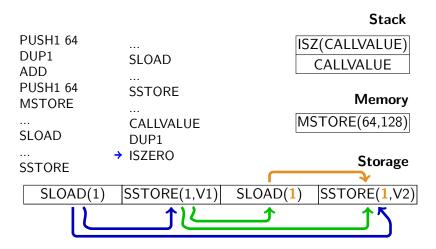
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- Apply simplification rules on memory Stack **PUSH1 64** ISZ(CALLVALUE) DUP1 **SLOAD CALLVALUE** ADD PUSH1 64 **SSTORE** Memory **MSTORE** MSTORE(64,128) **CALLVALUE** SLOAD. DUP1 ISZERO Storage **SSTORE** SSTORE(1,V1) SLOAD(1) SSTORE(1,V2) SLOAD(1)

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- Extension to other uninterpreted functions: if $B(\ldots,A(\ldots),\ldots)$ then $A \sqsubset B$
 - In previous example, CALLVALUE

 ☐ ISZ(CALLVALUE)

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$$s2 = SHL(96, s1)$$
 $s3 = AND(1.158 \times 10^{29}, s2)$

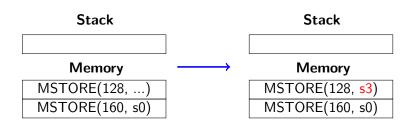
Stack

Memory

MSTORE(128, ...)
MSTORE(160, s0)

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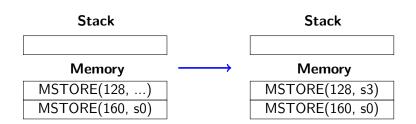
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 - 3 Bounds on the number of opcodes and on the size of the stack

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 - Abstract all the non-store subexpressions that appear in the SMS
 - Sounds on the number of opcodes and on the size of the stack

s2 = SHL(96, s1) s3 = AND(1.158
$$\times$$
 10²⁹, s2)

maxLn = 10 skSz = 5

Stack Stack

Memory Memory

MSTORE(128, ...)

MSTORE(128, s3)

MSTORE(160, s0)

MSTORE(160, s0)

Complete encoding

- Complete encoding
 - Constraint to describe the initial stack

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 - Constraint to describe the initial stack
 - 2 Constraint to describe the target stack

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$$\mathsf{t}_i = \mathsf{DUP}k \to$$

$$\neg u_{skSz-1,j} \land u_{k-1,j} \land u_{0,j+1} \land x_{0,j+1} = x_{k-1,j} \land MoveRest$$

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- ► SMT formula ⇒ hard constraints
- ► Cost of every EVM instruction ⇒ soft constraints
- ► Two different criteria to optimize:

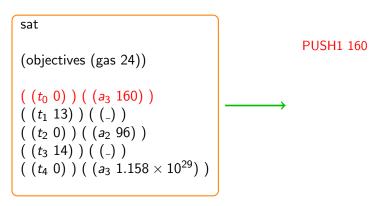
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- ► The cost of the solution can be expressed in terms of the cost of every single instruction
- ► SMT formula ⇒ hard constraints
- ► Cost of every EVM instruction ⇒ soft constraints
- ► Two different criteria to optimize:
 - ★ Gas model
 - ★ Bytes-size model

```
sat  (\text{objectives (gas 24)})   ( (t_0 \ 0) \ ) \ ( (a_3 \ 160) \ )   ( (t_1 \ 13) \ ) \ ( (-) \ )   ( (t_2 \ 0) \ ) \ ( (a_2 \ 96) \ )   ( (t_3 \ 14) \ ) \ ( (-) \ )   ( (t_4 \ 0) \ ) \ ( (a_3 \ 1.158 \times 10^{29}) \ )
```



```
sat
                                                 PUSH1 160
(objectives (gas 24))
                                                 MSTORE
((t_0 \ 0))((a_3 \ 160))
((t_1 \ 13))((_-))
((t_2 0))((a_2 96))
((t_3 14))((_-))
((t_4 \ 0))((a_3 \ 1.158 \times 10^{29}))
```

```
sat
                                                 PUSH1 160
(objectives (gas 24))
                                                 MSTORE
                                                 PUSH1 96
((t_0 \ 0))((a_3 \ 160))
((t_1 \ 13))((_-))
((t_2 0))((a_2 96))
((t_3 14))((_-))
((t_4 \ 0))((a_3 \ 1.158 \times 10^{29}))
```

```
sat
                                                 PUSH1 160
(objectives (gas 24))
                                                 MSTORE
                                                 PUSH1 96
                                                 SHL
((t_0 \ 0))((a_3 \ 160))
((t_1 \ 13))((_-))
((t_2 0))((a_2 96))
((t_3 14))((_-))
((t_4 \ 0)) ((a_3 \ 1.158 \times 10^{29}))
```

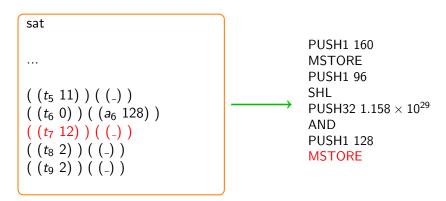
```
sat
                                                    PUSH1 160
(objectives (gas 24))
                                                    MSTORE
                                                    PUSH1 96
                                                    SHI
((t_0 \ 0))((a_3 \ 160))
                                                    PUSH32 1.158 \times 10<sup>29</sup>
((t_1 \ 13))((_-))
((t_2 0))((a_2 96))
((t_3 14))((_-))
((t_4 \ 0))((a_3 \ 1.158 \times 10^{29}))
```

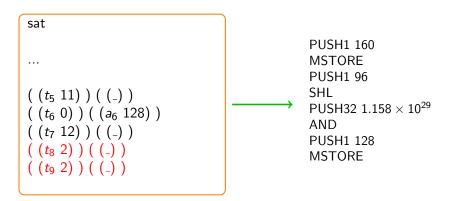
```
sat
                                                PUSH1 160
                                                MSTORE
. . .
                                                PUSH1 96
                                                SHI
((t_5 11))((_{-}))
                                                PUSH32 1.158 \times 10^{29}
((t_6 \ 0))((a_6 \ 128))
                                                AND
((t_7 12))((_-))
((t_8 2))((_-))
((t_9 2))((_-))
```

```
sat

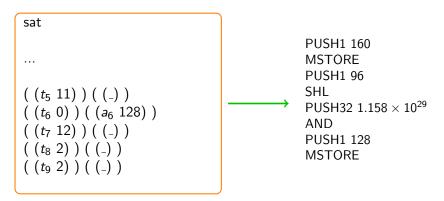
...

((t_{5} 11))((_{-}))
((t_{6} 0))((a_{6} 128))
((t_{7} 12))((_{-}))
((t_{8} 2))((_{-}))
((t_{9} 2))((_{-}))
```





- The optimized bytecode is obtained from the model together with the cost:
- Initial block consumes 48 gas and 22 bytes



- The optimized bytecode is obtained from the model together with the cost:
- Initial block consumes 48 gas and 22 bytes
- Final block consumes 24 gas and 43 bytes

```
sat
                                               PUSH1 160
                                               MSTORE
. . .
                                               PUSH1 96
                                               SHI
((t_5 11))((_-))
                                               PUSH32 1.158 \times 10^{29}
((t_6 \ 0))((a_6 \ 128))
                                               AND
((t_7 12))((_-))
                                               PUSH1 128
((t_8 2))((_-))
                                               MSTORE
((t_9 2))((_-))
```

Conclusions

- Analysis and optimization of Ethereum smart contracts is a popular research topic
 - There are tools based on symbolic execution, SMT solving or certified programming for detecting security vulnerabilities
- Presented tools:
 - GASTAP
 - ★ estimate the gas fee for running transactions
 - * attackers: estimate how much *Ether* an adversary has to pour into a contract in order to execute an out-of-gas attack
 - ★ analyzer that measures several resources
 - GASOL
 - ★ optimize storage accesses at Solidity level
 - ★ optimize the gas fee for running transactions and bytes-size
 - ★ Superoptimization and Max-SMT solver
 - tools applied to thousands of real smart contracts